## Deriving " $\tau_p$ = 63.2% of Process Step Response" Rule

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To derive the "time constant,  $\tau_P = 63.2\%$  of Process Step Response" rule used in model fitting, we must solve a linear first order ordinary differential equation (ODE):

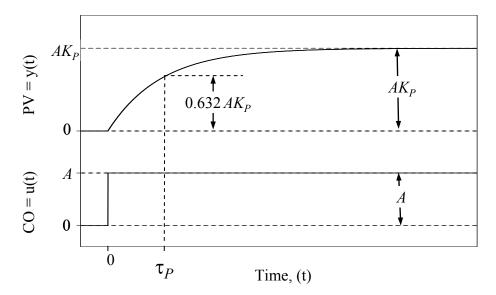


Figure 1 – Response of true first order process to a step change in controller output

The figure above shows the open loop step response of a true first order process model:

$$\tau_P \frac{dy(t)}{dt} + y(t) = K_P u(t) \quad \text{where} \quad y(0) = 0$$

As shown in Fig 1, the measured process variable, y(t), and controller output signal, u(t), are initially at steady state with y(t) = u(t) = 0 for t < 0. Other parameters include the process time constant,  $\tau_P$ , and process gain,  $K_P$ .

At time t = 0, the controller output is stepped to u(t) = A, where it remains for the duration of the experiment. Hence, the first order model becomes

$$\tau_P \frac{dy(t)}{dt} + y(t) = AK_P$$

Copyright © 2006 by Douglas J. Cooper All rights reserved To solve this ODE, rearrange as:

$$\frac{dy(t)}{dt} + \frac{1}{\tau_P} y(t) = \frac{AK_P}{\tau_P}$$

First compute the integrating factor,  $\mu = e^{\int (1/\tau_p)dt} = e^{t/\tau_p}$ . Solving the ODE using this integrating factor yields

$$y(t) = \frac{1}{e^{t/\tau_P}} \left[ \int e^{t/\tau_P} \left( \frac{AK_P}{\tau_P} \right) dt + c_1 \right]$$
$$= e^{-t/\tau_P} \left[ \frac{AK_P}{\tau_P} \int e^{t/\tau_P} dt + c_1 \right]$$

$$\int e^{ax} dx = \frac{1}{a} e^{ax}$$

 $\int e^{t/\tau_P} dt = \tau_P e^{t/\tau_P}$ 

and thus

so

$$y(t) = e^{-t/\tau_P} \left[ AK_P e^{t/\tau_P} + c_1 \right]$$

 $= AK_P + c_1 e^{-t/\tau_P}$ 

Next, apply the initial condition: (a) t = 0, y = 0,  $0 = AK_P + c_1$ , and thus  $c_1 = -AK_P$ .

Substituting and rearranging, we obtain the solution to the ODE:

$$y(t) = AK_P \left[ 1 - e^{-t/\tau_P} \right]$$

After the passage of one time constant, time  $t = \tau_P$ , the solution becomes

$$y(\tau_P) = AK_P \left[ 1 - e^{-\tau_P / \tau_P} \right] = AK_P \left[ 1 - e^{-1} \right]$$

Therefore, the measured process variable step response at time  $t = \tau_P$  is

$$y(\tau_P) = 0.632 A K_P$$

As we set out to show, at time *t* equals one time constant,  $\tau_P$ , the measured process variable, y(t), will have traveled to 63.2% of the total change that it will ultimately experience.

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